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Traces the history of robotics and introduces a computer engineering student named Eletha Flores.

This book is for musical makers and artists who want to gain knowledge and inspiration for your own amazing creations. "Grumpy Mike" Cook, co-author of several books on the Raspberry Pi and frequent answerer of questions of the Arduino forums, brings you a fun and instructive mix and simple and complex projects to help you understand how the Arduino can work with the MIDI system to create musical instruments and manipulate sound. In Part I you'll find a set of projects to show you the possibilities of MIDI plus Arduino, covering both the hardware and software aspects of creating musical instruments. In Part II, you learn how to directly synthesize a wave form to create your own sounds with Arduino and concludes with another instrument project: the SpoonDuino. Finally, in Part III, you'll learn about signal processing with the Arduino Uno and the Due — how to create effects like delay, echo, pitch changes, and realtime backwards audio output. /divIf you want to learn more about how to create music, instruments, and sound effects with Arduino, then get on board for Grumpy Mike's grand tour with Arduino Music and Sound Projects.

Mechanical Vibrations, 6/e is ideal for undergraduate courses in Vibration Engineering. Retaining the style of its previous editions, this text presents the theory, computational aspects, and applications of vibrations in as simple a manner as possible. With an emphasis on computer techniques of analysis, it gives expanded explanations of the fundamentals, focusing on physical significance and interpretation that build upon students' previous experience. Each self-contained topic fully explains all concepts and presents the derivations with complete details. Numerous examples and problems illustrate principles and concepts.

Tomorrow's robots, which includes the humanoid robot, can perform task like tutoring children, working as tour guides, driving humans to and from work, do the family shopping etc. Tomorrow's robots will enhance lives in ways we never dreamed possible. No time to attend the decisive meeting on Asian strategy? Let your robot go for you and make the decisions. Not feeling well enough to go to the clinic? Let Dr Robot come to you, make a diagnosis, and get you the necessary medicine for treatment. No time to coach the soccer team this week? Let the robot do it for you. Tomorrow's robots will be the most exciting and revolutionary things to happen to the world since the invention of the automobile. It will change the way we work, play, think, and live. Because of this, nowadays robotics is one of the most dynamic fields of scientific research. These days, robotics is offered in almost every university in the world. Most mechanical engineering departments offer a similar course at both the undergraduate and graduate levels. And increasingly, many computer and electrical engineering departments are also offering it. This book will guide you, the curious beginner, from yesterday to tomorrow. The book will cover practical knowledge in understanding, developing, and using robots as versatile equipment to automate a variety of industrial processes or tasks. But, the book will also discuss the possibilities we can look forward to when we are capable of creating a vision-guided, learning machine.

Methods in Stream Ecology, Second Edition, provides a complete series of field and laboratory protocols in stream ecology that are ideal for teaching or conducting research. This updated edition reflects recent advances in the technology associated with ecological assessment of streams, including remote sensing. In addition, the relationship between stream flow and alluviation has been added, and a new chapter on riparian zones is also included. The book features exercises in each chapter; detailed instructions, illustrations, formulae, and data sheets for in-field research for students; and taxonomic keys to common stream invertebrates and algae. With a student-friendly price, this book is key for all students and researchers in stream and freshwater ecology, freshwater biology, marine ecology, and river ecology. This text is also supportive as a supplementary text for courses in watershed ecology/science, hydrology, fluvial geomorphology, and landscape ecology. Exercises in each chapter Detailed instructions, illustrations, formulae, and data sheets for in-field research for students Taxonomic keys to common stream invertebrates and algae Link from Chapter 22: FISH COMMUNITY COMPOSITION to an interactive program for assessing and modeling fish numbers

Newtonian mechanics : dynamics of a point mass (1001-1108) - Dynamics of a system of point masses (1109-1144) - Dynamics of rigid bodies (1145-1223) - Dynamics of deformable bodies (1224-1272) - Analytical mechanics : Lagrange's equations (2001-2027) - Small oscillations (2028-2067) - Hamilton's canonical equations (2068-2084) - Special relativity (3001-3054).

This book presents an account of innovative methods and, for most of them, gives direct and practical insights into how practitioners can benefit from their use in their everyday practice. It also explains how to interpret the data measured, and the underlying neuromechanical and biomechanical factors related to sports performance. Written and edited by the same researchers who proposed and validated these methods, this book not only presents innovative methods for an efficient training and testing process (most of which are based on very simple technology and data processing methods), but also discusses the associated background information. Although it is a young scientific discipline, sport biomechanics has taken on an important role in routine sports training, medicine and rehabilitation. It allows both a better understanding of human locomotion and performance and better design of training and injury prevention. In those processes, the testing of athletes is crucial, and the quality and quantity of the variables analysed directly influences the efficiency of physicians', coaches', physiotherapists' and other practitioners' interventions.

Mechanical engineering, an engineering discipline borne of the needs of the industrial revolution, is once again asked to do its substantial share in the call for industrial renewal. The general call is urgent as we face profound issues of productivity and competitiveness that require engineering solutions, among others. The Mechanical Engineering Series features graduate texts and research monographs intended to address the need for information in contemporary areas of mechanical engineering. The series is conceived as a comprehensive one that covers a broad range of concentrations important to mechanical engineering graduate education and research. We are fortunate to have a distinguished roster of consulting editors on the advisory board, each an expert in one of the areas of concentration. The names of the consulting editors are listed on the next page of this volume. The areas of concentration are: applied mechanics; biomechanics; computational mechanics; dynamic systems and control; energetics; mechanics of materials; processing; thermal science; and tribology.

How can geckoes walk on the ceiling and basilisk lizards run over water? What are the aerodynamic effects that enable small insects to fly? What are the relative merits of squids' jet-propelled swimming and fishes' tail-powered swimming? Why do horses change gait as they increase speed? What determines our own vertical leap? Recent technical advances have greatly increased researchers' ability to answer these questions with certainty and in detail. This text provides an up-to-date overview of how animals run, walk, jump, crawl, swim, soar, hover, and fly. Excluding only the tiny creatures that use cilia, it covers all animals that power their movements with muscle—from roundworms to whales, clams to elephants, and gnats to albatrosses. The introduction sets out the general rules governing all modes of animal locomotion and considers the performance criteria—such as speed, endurance, and economy—that have shaped their selection. It introduces energetics and optimality as basic principles. The text then tackles each of the major modes by which animals move on land, in water, and through air. It explains the mechanisms involved and the physical and biological forces shaping those mechanisms, paying particular attention to energy costs. Focusing on general principles but extensively discussing a wide variety of individual cases, this is a superb synthesis of current knowledge about animal locomotion. It will be enormously useful to advanced undergraduates, graduate students, and a range of professional biologists, physicists, and engineers.

For this revision of their bestselling junior- and senior-level text, Guru and Hizioglu have incorporated eleven years of cutting-edge developments in the field since Electric Machinery and Transformers was first published. Completely re-written, the new Second Edition also incorporates suggestions from students and instructors who have used the First Edition, making it the best text available for junior- and senior-level courses in electric machines. The new edition features a wealth of new and improved problems and examples, designed to complement the authors' overall goal of encouraging intuitive reasoning rather than rote memorization of material. Chapter 3, which presents the conversion of energy, now includes: analysis of magnetically coupled coils, induced emf in a coil rotating in a uniform magnetic field, induced emf in a coil rotating in a time-varying magnetic field, and the concept of the revolving field. All problems and examples have been rigorously tested using Mathcad.

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