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Openstreetmap and programming. It presents a thorough introduction to the use of available global positioning data for the development of applications involving digital maps. The author first describes the different formats of GPS data and digital maps and shows how to use recorded GPS traces to replay and display this data on a

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digital map. Then, he works through in detail the processing steps of obtaining dedicated data from OpenStreetMaps and how to extract a network for a simple navigation application. For each topic covered—GPS data, OpenStreetMaps, and navigation—Java code is developed that can easily be adapted to the readers' needs

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and locality. Finally, all components are put together in a sample computer-game application modeled on the well-known board game, Scotland Yard. The computer game is intended to be a basis from which readers can develop and customize their own application for their desired geographical area. The developed

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Application can be "published" on the Internet and made available for interactive multiplayer competition. This book provides a fun and interesting way to learn distributed programming with Java and real-world data. Open-source software is available on a companion website at [www.roaf.de](http://www.roaf.de)

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Be your own cartographer.

GPS Tracking with Java EE Components:  
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how the self-driving car is actually  
changing the automotive industry, from  
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Services and data crunching, in real time, with really big data. The book analyzes how the challenges of the Self Driving Car (SDC) exceed the limits of a classical GPS Tracking System (GTS.) It provides a guidebook on setting up a tracking system by customizing its components. It also provides an overview of the prototyping

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and modeling process, and how the reader can modify this process for his or her own software. Every component is introduced in detail and includes a number of design decisions for development. The book introduces Java EE (JEE) Modules, and shows how they can be combined to a customizable GTS, and used as seed

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Components to enrich existing systems with live tracking. The book also explores how to merge tracking and mapping to guide SDCs, and focuses on client server programming to provide useful information. It also discusses the challenges involved with the live coordination of moving cars. This book is

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designed to aid GTS developers and engineers in the automotive industry. It can also help Java Developers, not only interested in GPS Tracking, but in modern software design from many individual modules. Source code and sample applications will be available on the book's website.

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"Websites like MapQuest and Google Maps have transformed the way we think about maps. But these services do more than offer driving directions, they provide APIs that web developers can use to build highly customized map-based applications. The author, Adam

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DuVander, delivers 73 useful scripts, examples that will show you how to create interactive maps and mashups." --[book cover]

Maps are a fundamental resource in a diverse array of applications ranging from everyday activities, such as route planning

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through the legal demarcation of space to scientific studies, such as those seeking to understand biodiversity and inform the design of nature reserves for species conservation. For a map to have value, it should provide an accurate and timely representation of the phenomenon depicted and this can be a challenge in a

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dynamic world. Fortunately, mapping activities have benefitted greatly from recent advances in geoinformation technologies. Satellite remote sensing, for example, now offers unparalleled data acquisition and authoritative mapping agencies have developed systems for the routine production of maps in accordance

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with strict standards. Until recently, much mapping activity was in the exclusive realm of authoritative agencies but technological development has also allowed the rise of the amateur mapping community. The proliferation of inexpensive and highly mobile and location aware devices together with Web

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2.0 technology have fostered the emergence of the citizen as a source of data. Mapping presently benefits from vast amounts of spatial data as well as people able to provide observations of geographic phenomena, which can inform map production, revision and evaluation. The great potential of these developments is,

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however, often limited by concerns. The latter span issues from the nature of the citizens through the way data are collected and shared to the quality and trustworthiness of the data. This book reports on some of the key issues connected with the use of citizen sensors in mapping. It arises from a European Co-

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operation in Science and Technology  
(COST) Action, which explored issues  
linked to topics ranging from citizen  
motivation, data acquisition, data quality  
and the use of citizen derived data in the  
production of maps that rival, and  
sometimes surpass, maps arising from  
authoritative agencies.

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The five-volume set LNCS 7971-7975 constitutes the refereed proceedings of the 13th International Conference on Computational Science and Its Applications, ICCSA 2013, held in Ho Chi Minh City, Vietnam in June 2013. The 248 revised papers presented in five tracks

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and 33 special sessions and workshops were carefully reviewed and selected. The 46 papers included in the five general tracks are organized in the following topical sections: computational methods, algorithms and scientific applications; high-performance computing and networks; geometric modeling, graphics

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and visualization; advanced and emerging applications; and information systems and technologies. The 202 papers presented in special sessions and workshops cover a wide range of topics in computational sciences ranging from computational science technologies to specific areas of computational sciences such as computer

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Truly revolutionary: now you can write geolocation applications directly in the browser, rather than develop native apps for particular devices. This concise book demonstrates the W3C Geolocation API in action, with code and examples to help

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Open build HTML5 apps using the "write once, deploy everywhere" model. Along the way, you get a crash course in geolocation, browser support, and ways to integrate the API with common geo tools like Google Maps. Ideal for experienced JavaScript developers. Learn how geo information is gathered from different

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Sources, depending on the device Discover how coordinate systems work, including geodetic systems and datums Use the API to collect location information from a user's browser with JavaScript code Place geo information on a map using the Google Maps or ArcGIS JavaScript APIs Save geo data with databases, the Keyhole

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Markup Language, or the shapefile format  
Be familiar with several practical uses for  
geo data, such as geomarketing, geosocial,  
geotagging, and geo-applications

This book is a printed edition of the  
Special Issue "Advances in Multi-Sensor  
Information Fusion: Theory and

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Applications 2017" that was published in  
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"Jobs in data science abound, but few  
people have the data science skills needed  
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Geocomputation with R is for people who want to analyze, visualize and model

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geographic data with open source software. It is based on R, a statistical programming language that has powerful data processing, visualization, and geospatial capabilities. The book equips you with the knowledge and skills to tackle a wide range of issues manifested in geographic data, including those with

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scientific, societal, and environmental implications. This book will interest people from many backgrounds, especially Geographic Information Systems (GIS) users interested in applying their domain-specific knowledge in a powerful open source language for data science, and R users interested in extending their skills to

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Handle spatial data. The book is divided into three parts: (I) Foundations, aimed at getting you up-to-speed with geographic data in R, (II) extensions, which covers advanced techniques, and (III) applications to real-world problems. The chapters cover progressively more advanced topics, with early chapters

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providing strong foundations on which the later chapters build. Part I describes the nature of spatial datasets in R and methods for manipulating them. It also covers geographic data import/export and transforming coordinate reference systems. Part II represents methods that build on these foundations. It covers

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advanced map making (including web mapping), "bridges" to GIS, sharing reproducible code, and how to do cross-validation in the presence of spatial autocorrelation. Part III applies the knowledge gained to tackle real-world problems, including representing and modeling transport systems, finding

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optimal locations for stores or services,  
and ecological modeling. Exercises at the  
end of each chapter give you the skills  
needed to tackle a range of geospatial  
problems. Solutions for each chapter and  
supplementary materials providing  
extended examples are available at [https://  
geocompr.github.io/geocompkg/articles/](https://geocompr.github.io/geocompkg/articles/).

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Dr. Robin Lovelace is a University Academic Fellow at the University of Leeds, where he has taught R for geographic research over many years, with a focus on transport systems. Dr. Jakub Nowosad is an Assistant Professor in the Department of Geoinformation at the Adam Mickiewicz University in Poznan,

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where his focus is on the analysis of large datasets to understand environmental processes. Dr. Jannes Muenchow is a Postdoctoral Researcher in the GIScience Department at the University of Jena, where he develops and teaches a range of geographic methods, with a focus on ecological modeling, statistical

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geocomputing, and predictive mapping.

All three are active developers and work on a number of R packages, including stplanr, sabre, and RQGIS.

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