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Handbook of Unmanned Aerial Vehicles: Kimon P. Valavanis ...

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Handbook of Unmanned Aerial Vehicles - Kimon P Valavanis ...

Abstract This chapter discusses the payload design issues for small unmanned aerial vehicles (UAVs). Details of several payload design principles to overcome various small UAV constraints imposed by stringent weight, power, and volume are discussed.

UAV Handbook: Payload Design of Small UAVs | SpringerLink

The Handbook of Unmanned Aerial Vehicles is a reference text for the academic and research communities, industry, manufacturers, users, practitioners, Federal Government, Federal and State Agencies, the private sector, as well as all organizations that are and will be using unmanned aircraft in a wide spectrum of applications. The Handbook covers all aspects of UAVs, from design to logistics ...

The Handbook of Unmanned Aerial Vehicles is a reference text for the academic and research communities, industry, manufacturers, users, practitioners, Federal Government, Federal and State Agencies, the private sector, as well as all organizations that are and will be using unmanned aircraft in a wide spectrum of applications. The Handbook covers all aspects of UAVs, from design to logistics and ethical issues. It is also targeting the young investigator, the future inventor and entrepreneur by providing an overview and detailed information of the state-of-the-art as well as useful new concepts that may lead to innovative research. The contents of the Handbook include material that addresses the needs and 'know how' of all of the above sectors targeting a very diverse audience. The Handbook offers a unique and comprehensive treatise of everything one needs to know about unmanned aircrafts, from conception to operation, from technologies to business activities, users, OEMs, reference sources, conferences, publications, professional societies, etc. It should serve as a Thesaurus, an indispensable part of the library for everyone involved in this area. For the first time, contributions by the world's top experts from academia, industry, government and the private sector, are brought together to provide unique perspectives on the current state-of-the-art in UAV, as well as future directions. The Handbook is intended for the expert/practitioner who seeks specific technical/business information, for the technically-oriented scientists and engineers, but also for the novice who wants to learn more about the status of UAV and UAV-related technologies. The Handbook is arranged in a user-friendly format, divided into main parts referring to: UAV Design Principles; UAV Fundamentals; UAV Sensors and Sensing Strategies; UAV Propulsion; UAV Control; UAV Communication Issues; UAV Architectures; UAV Health Management Issues; UAV Modeling, Simulation, Estimation and Identification; MAVs and Bio-Inspired UAVs; UAV Mission and Path Planning; UAV Autonomy; UAV Sense, Detect and Avoid Systems; Networked UAVs and UAV Swarms; UAV Integration into the National Airspace; UAV-Human Interfaces and Decision Support Systems; Human Factors and Training; UAV Logistics Support; UAV Applications; Social and Ethical Implications; The Future of UAVs. Each part is written by internationally renowned authors who are authorities in their respective fields. The contents of the Handbook supports its unique character as a thorough and comprehensive reference book directed to a diverse audience of practitioners, businesses, users and potential users, managers and decision makers, novices and experts, who seek a holistic volume of information that is not only a technical treatise but also a source for answers to several questions on UAV manufacturers, users, major players in UAV research, costs, training required and logistics issues.

The Handbook of Unmanned Aerial Vehicles is a reference text for the academic and research communities, industry, manufacturers, users, practitioners, Federal Government, Federal and State Agencies, the private sector, as well as all organizations that are and will be using unmanned aircraft in a wide spectrum of applications

Unmanned aerial vehicles (UAVs) are being increasingly used in different applications in both military and civilian domains. These applications include surveillance, reconnaissance, remote sensing, target acquisition, border patrol, infrastructure monitoring, aerial imaging, industrial inspection, and emergency medical aid. Vehicles that can be considered autonomous must be able to make decisions and react to events without direct intervention by humans. Although some UAVs are able to perform increasingly complex autonomous maneuvers, most UAVs are not fully autonomous; instead, they are mostly operated remotely by humans. To make UAVs fully autonomous, many technological and algorithmic developments are still required. For instance, UAVs will need to improve their sensing of obstacles and subsequent avoidance. This becomes particularly important as autonomous UAVs start to operate in civilian airspaces that are occupied by other aircraft. The aim of this volume is to bring together the work of leading researchers and practitioners in the field of unmanned aerial vehicles with a common interest in their autonomy. The contributions that are part of this volume present key challenges associated with the autonomous control of unmanned aerial vehicles, and propose solution methodologies to address such challenges, analyse the proposed methodologies, and evaluate their performance.

Autonomous unmanned air vehicles (UAVs) are critical to current and future military, civil, and commercial operations. Despite their importance, no previous textbook has accessibly introduced UAVs to students in the engineering, computer, and science disciplines–until now. Small Unmanned Aircraft provides a concise but comprehensive description of the key concepts and technologies underlying the dynamics, control, and guidance of fixed-wing unmanned aircraft, and enables all students with an introductory-level background in controls or robotics to enter this exciting and important area. The authors explore the essential underlying physics and sensors of UAV problems, including low-level autopilot for stability and higher-level autopilot functions of path planning. The textbook leads the student from rigid-body dynamics through aerodynamics, stability augmentation, and state estimation using onboard sensors, to maneuvering through obstacles. To facilitate understanding, the authors have replaced traditional homework assignments with a simulation project using the MATLAB/Simulink environment. Students begin by modeling rigid-body dynamics, then add aerodynamics and sensor models. They develop low-level autopilot code, extended Kalman filters for state estimation, path-following routines, and high-level path-planning algorithms. The final chapter of the book focuses on UAV guidance using machine vision. Designed for advanced undergraduate or graduate students in engineering or the sciences, this book offers a bridge to the aerodynamics and control of UAV flight.

Written by an expert with more than 30 years of experience, Guidance of Unmanned Aerial Vehicles contains new analytical results, taken from the author's research, which can be used for analysis and design of unmanned aerial vehicles guidance and control systems. This book progresses from a clear elucidation of guidance laws and unmanned aerial vehicle dynamics to the modeling of their guidance and control systems. Special attention is paid to guidance of autonomous UAVs, which differs from traditional missile guidance. The author explains UAV applications, contrasting them to a missile's limited ability (or inability) to control axial acceleration. The discussion of guidance laws for UAVs presents a generalization of missile guidance laws developed by the author. The computational algorithms behind these laws are tested in three applications—for the surveillance problem, the refueling problem, and for the motion control of a swarm of UAVs. The procedure of choosing and testing the guidance laws is also considered in an example of future generation of airborne interceptors launched from UAVs. The author provides an innovative presentation of the theoretical aspects of unmanned aerial vehicles' guidance that cannot be found in any other book. It presents new ideas that, once crystallized, can be implemented in the new generation of unmanned aerial systems.

Unmanned Aircraft Systems delivers a much needed introduction to UAV System technology, taking an integrated approach that avoids compartmentalising the subject. Arranged in four sections, parts 1-3 examine the way in which various engineering disciplines affect the design, development and deployment of UAS. The fourth section assesses the future challenges and opportunities of UAS. Technological innovation and increasingly diverse applications are two key drivers of the rapid expansion of UAS technology. The global defence budget for UAS procurement is expanding, and in the future the market for civilian UAVs is expected to outmatch that of the military. Agriculture, meteorology, conservation and border control are just a few of the diverse areas in which UAVs are making a significant impact; the author addresses all of these applications, looking at the roles and technology behind both fixed wing and rotorcraft UAVs. Leading aeronautical consultant Reg Austin co-founded the Bristol International Remotely Piloted Vehicle (RPV) conferences in 1979, which are now the longest-established UAS conferences worldwide. In addition, Austin has over 40 years' experience in the design and development of UAS. One of Austin's programmes, the "Sprite UAV System" has been deployed around the world and operated by day and night, in all weathers.

First used in military applications, unmanned aerial vehicles are becoming an integral aspect of modern society and are expanding into the commercial, scientific, recreational, agricultural, and surveillance sectors. With the increasing use of these drones by government officials, business professionals, and civilians, more research is needed to understand their complexity both in design and function. Unmanned Aerial Vehicles: Breakthroughs in Research and Practice is a critical source of academic knowledge on the design, construction, and maintenance of drones, as well as their applications across all aspects of society. Highlighting a range of pertinent topics such as intelligent systems, artificial intelligence, and situation awareness, this publication is an ideal reference source for military consultants, military personnel, business professionals, operation managers, surveillance companies, agriculturalists, policymakers, government officials, law enforcement, IT professionals, academicians, researchers, and graduate-level students.

Small Unmanned Fixed-wing Aircraft Design is the essential guide to designing, building and testing fixed wing UAVs (or drones). It deals with aircraft from two to 150 kg in weight and is based on the first-hand experiences of the world renowned UAV team at the UK's University of Southampton. The book covers both the practical aspects of designing, manufacturing and flight testing and outlines the essential calculations needed to underpin successful designs. It describes the entire process of UAV design from requirements definition to configuration layout and sizing, through preliminary design and analysis using simple panel codes and spreadsheets to full CFD and FEA models and on to detailed design with parametric CAD tools. Its focus is on modest cost approaches that draw heavily on the latest digital design and manufacturing methods, including a strong emphasis on utilizing off-the-shelf components, low cost analysis, automated geometry modelling and 3D printing. It deliberately avoids a deep theoretical coverage of aerodynamics or structural mechanics; rather it provides a design team with sufficient insights and guidance to get the essentials undertaken more pragmatically. The book contains many all-colour illustrations of the dozens of aircraft built by the authors and their students over the last ten years giving much detailed information on what works best. It is predominantly aimed at under-graduate and MSc level student design and build projects, but will be of interest to anyone engaged in the practical problems of getting quite complex unmanned aircraft flying. It should also appeal to the more sophisticated aero-modeller and those engaged on research based around fixed wing UAVs.

Introduction to Unmanned Aircraft Systems surveys the fundamentals of unmanned aircraft system (UAS) operations, from sensors, controls, and automation to regulations, safety procedures, and human factors. It is designed for the student or layperson and thus assumes no prior knowledge of UASs, engineering, or aeronautics. Dynamic and well-illustrated, the first edition of this popular primer was created in response to a need for a suitable university-level textbook on the subject. Fully updated and significantly expanded, this new Second Edition: Reflects the proliferation of technological capability, miniaturization, and demand for aerial intelligence in a post-9/11 world Presents the latest major commercial uses of UASs and unmanned aerial vehicles (UAVs) Enhances its coverage with greater depth and support for more advanced coursework Provides material appropriate for introductory UAS coursework in both aviation and aerospace engineering programs Introduction to Unmanned Aircraft Systems, Second Edition capitalizes on the expertise of contributing authors to instill a practical, up-to-date understanding of what it takes to safely operate UASs in the National Airspace System (NAS). Complete with end-of-chapter discussion questions, this book makes an ideal textbook for a first course in UAS operations.